

EAST Search History

| Ref # | Hits | Search Query | DBs | Default Operator | Plurals | Time Stamp |
|-------|-------|---|--------------------|------------------|---------|---------------------|
| S14 | 0 | "3623566" | US-PGPUB | OR | OFF | 2008/12/16 13:22 |
| S15 | 12 | "3623566" | US-PGPUB; USPAT | OR | OFF | 2008/12/16 13:22 |
| S16 | 5 | arce-diaz and robot | US-PGPUB; USPAT | OR | OFF | 2008/12/16 14:26 |
| S17 | 0 | 180/8.1,8.2,8.5,8.6,6.5.cds. and (toe and (bending adj angle)) | US-PGPUB; USPAT | OR | OFF | 2008/12/16 14:32 |
| S18 | 4 | 180/8.1,8.2,8.5,8.6,6.5.cds. and (toe and (bending adj angle)) | US-PGPUB; USPAT | OR | OFF | 2008/12/16 14:32 |
| S19 | 0 | furuta and (two-legged adj walking) | US-PGPUB | OR | OFF | 2008/12/17 09:41 |
| S20 | 0 | furuta and (two-legged adj walking) | US-PGPUB; USPAT | OR | OFF | 2008/12/17 09:41 |
| S21 | 61 | furuta and (walking) | US-PGPUB; USPAT | OR | OFF | 2008/12/17 09:41 |
| S22 | 114 | takenaka and (legged adj mobile adj robot) | US-PGPUB; USPAT | OR | OFF | 2008/12/17 09:53 |
| S23 | 114 | takenaka and (legged adj mobile adj robot and (control)) | US-PGPUB; USPAT | OR | OFF | 2008/12/17 09:53 |
| S24 | 659 | robot and (toe and (bending angle)) | US-PGPUB; USPAT | OR | OFF | 2008/12/17 09:55 |
| S25 | 26404 | robot and (toe adj bending angle) | US-PGPUB; USPAT | OR | OFF | 2008/12/17 09:55 |
| S26 | 1 | robot and (toe adj bending adj angle) | US-PGPUB; USPAT | OR | OFF | 2008/12/17 09:56 |
| S27 | 34 | robot and (toe and (bending adj angle)) | US-PGPUB; USPAT | OR | OFF | 2008/12/17 09:56 |
| S28 | 2 | "6431665" | US-PGPUB; USPAT | OR | OFF | 2008/12/17 11:54 |
| S29 | 88 | "4574649" | US-PGPUB; USPAT | OR | OFF | 2008/12/17 12:06 |
| S30 | 2 | ("2965259").PN. | USPAT; USOCR | OR | OFF | 2008/12/23 10:09 |
| S31 | 1 | ("7044259").PN. | USPAT; USOCR | OR | OFF | 2008/12/29 16:41 |

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|-----|------|---|------------------------------|----|-----|---------------------|
| S32 | 26 | ("3595334" "3637036" "3641765" "3656570" "3823792" "3841423" "3858675" "3865208" "3900075" "3910369" "3916625" "3978937" "4402181" "5427195" "5819870" "5823284" "5848664" "6062332" "6230829" "6276468" "6305486" "6321866" "6354392" "6663114" "6808036" "6904993").PN. | US-PGPUB; USPAT; USOCR | OR | OFF | 2008/12/29 16:45 |
| S33 | 1 | ("6267196").PN. | USPAT; USOCR | OR | OFF | 2008/12/30 10:21 |
| S34 | 1 | ("4056158").PN. | USPAT; USOCR | OR | OFF | 2008/12/30 10:24 |
| S35 | 557 | 318/568.12.cds. | USPAT | OR | OFF | 2008/12/31 17:46 |
| S36 | 174 | 318/568.12.cds. and (foot or toe) | USPAT | OR | OFF | 2008/12/31 17:46 |
| S37 | 198 | 901/1,2.cds. and (foot or toe) | USPAT | OR | OFF | 2008/12/31 17:47 |
| S38 | 2121 | robot and foot | US-PGPUB | OR | OFF | 2008/12/31 17:49 |
| S39 | 1 | robot and (toe adj angle) | US-PGPUB | OR | OFF | 2008/12/31 17:49 |
| S40 | 0 | robot and (foot and (toe near holder)) | US-PGPUB | OR | OFF | 2008/12/31 17:50 |
| S41 | 14 | robot and (foot and (toe near angle)) | US-PGPUB | OR | OFF | 2008/12/31 17:50 |

12/31/2008 8:46:19 PM

C:\Documents and Settings\marcediaz\My Documents\EAST\Workspaces\robot foot with
bendable toe.wsp